A Correlation of College Physics: A Strategic Approach 4th Edition, AP® Edition ©2019 4th Edition, AP® Edition Digital Update ©2023



To the AP[®] Physics 1 Course Framework Effective Fall 2024



Table of Contents

AP Physics 1 Course	Page
Unit 1: Kinematics (5 topics)	03
Unit 2: Force and Translational Dynamics (9 topics)	04
Unit 3: Work, Energy, and Power (5 topics)	06
Unit 4: Linear Momentum (4 topics)	07
Unit 5: Torque and Rotational Dynamics (6 topics)	08
Unit 6: Energy and Momentum of Rotating Systems (6 topics)	09
Unit 7: Oscillations (4 topics)	11
Unit 8: Fluids (4 topics)	12

The units above reflect the College Board's AP[®] Physics 1 Course Framework.



Unit 1: Kinematics (5 topics) AP® Physics 1 Course Framework		
Торіс	Learning Objectives	College Physics: A Strategic Approach Chapters and Sections
1.1 Scalars and Vectors in One dimension	1.1.A Describe a scalar or vector quantity using magnitude and direction, as appropriate.1.1.B Describe a vector sum in one dimension.	1.6 Vectors and Motion: A First Look
1.2 Displacement, Velocity, and Acceleration	1.2.A Describe a change in an object's position.1.2.B Describe the average velocity and acceleration of an object.	1.3 Position and Time: Putting Numbers on Nature1.4 Velocity1.6 Vectors and Motion: A First Look2.4 Acceleration
1.3 Representing Motion	1.3.A Describe the position, velocity, and acceleration of an object using representations of that object's motion.	2.1 Describing Motion2.2 Uniform Motion2.3 Instantaneous Velocity2.4 Acceleration2.5 Motion with Constant Acceleration2.7 Free Fall
1.4 Reference Frames and Relative Motion	 1.4.A Describe the reference frame of a given observer. 1.4.B Describe the motion of objects as measured by observers in different inertial reference frames. 	3.8 Relative Motion 27.2 Galilean Relativity
1.5 Vectors and Motion in Two Dimensions	 1.5.A Describe the perpendicular components of a vector. 1.5.B Describe the motion of an object moving in two dimensions. 	 3.1 Using Vectors 3.2 Coordinate Systems and Vector Components 3.3 Motion on a Ramp 3.4 Motion in Two Dimensions 3.5 Projectile Motion 3.6 Projectile Motion: Solving Problems



3

Unit 2: Force and Translational Dynamics (9 topics) AP® Physics 1 Course Framework		
Торіс	Learning Objectives	College Physics: A Strategic Approach Chapters and Sections
2.1 Systems and Center of Mass	 2.1.A Describe the properties and interactions of a system. 2.1.B Describe the location of a system's center of mass with respect to the system's constituent parts. 	7.4 Gravitational Torque and the Center of Gravity 9.4 Conservation of Momentum
2.2 Forces and Free- Body Diagrams	 2.2.A Describe a force as an interaction between two objects or systems. 2.2.B Describe the forces exerted on an object or system using a free-body diagram. 	4.1 Motion and Forces4.2 A Short Catalog of Forces4.3 Identifying Forces4.6 Free-Body Diagrams
2.3 Newton's Third Law	2.3.A Describe the interaction of two objects using Newton's third law and a representation of paired forces exerted on each object.	4.7 Newton's Third Law 5.7 Interacting Objects 5.8 Ropes and Pulleys
2.4 Newton's First Law	2.4.A Describe the conditions under which a system's velocity remains constant.	4.1 Motion and Forces
2.5 Newton's Second Law	2.5.A Describe the conditions under which a system's velocity changes.	4.4 What Do Forces Do?4.5 Newton's Second Law5.2 Dynamics and Newton's Second Law



4

Unit 2: Force and Translational Dynamics (9 topics) AP® Physics 1 Course Framework		
Торіс	Learning Objectives	College Physics: A Strategic Approach Chapters and Sections
2.6 Gravitational Force	2.6.A Describe the gravitational interaction between two objects or systems with mass.	 4.2 A Short Catalog of Forces 5.3 Mass and Weight 6.3 Apparent Forces in Circular Motion 6.4 Circular Orbits and Weightlessness
	2.6.B Describe situations in which the gravitational force can be considered constant.	6.5 Newton's Law of Gravity
	2.6.C Describe the conditions under which the magnitude of a system's apparent weight is different from the magnitude of the gravitational force exerted on that system.	
	2.6.D Describe inertial and gravitational mass.	
2.7 Kinetic and Static Friction	2.7.A Describe kinetic friction between two surfaces.	4.2 A Short Catalog of Forces 5.4 Normal Forces 5.5 Friction
	2.7.B Describe static friction between two surfaces.	
2.8 Spring Forces	2.8.A Describe the force exerted on an object by an ideal spring.	4.2 A Short Catalog of Forces 8.3 Springs and Hooke's Law



5

2.9 Circular Motion	2.9.A Describe the motion	3.7 Circular Motion
	of an object traveling in a	6.1 Uniform Circular Motion
	circular path.	6.2 Dynamics of Uniform Circular Motion
		6.4 Circular Orbits and Weightlessness
	2.9.B Describe circular	6.6 Gravity and Orbits
	orbits using Kepler's third	7.2 The Rotation of a Rigid Body
	law.	

Unit 3: Work, Energy, and Power (5 topics) AP® Physics 1 Course Framework		
Торіс	Learning Objectives	College Physics: A Strategic Approach Chapters and Sections
3.1 Translational Kinetic Energy	3.1.A Describe the translational kinetic energy of an object in terms of the object's mass and velocity.	10.1 The Basic Energy Model 10.3 Kinetic Energy
3.2 Work	3.2.A Describe the work done on an object or system by a given force or collection of forces.	10.1 The Basic Energy Model 10.2 Work 10.5 Thermal Energy
3.3 Potential Energy	3.3.A Describe the potential energy of a system.	10.1 The Basic Energy Model 10.4 Potential Energy
3.4 Conservation of Energy	 3.4.A Describe the energies present in a system. 3.4.B Describe the behavior of a system using conservation of mechanical energy principles. 3.4.C Describe how the selection of a system determines whether the energy of that system changes. 	10.1 The Basic Energy Model 10.6 Conservation of Energy 10.7 Energy Diagrams



6

3.5 Power	3.5.A Describe the transfer of energy into, out of, or within a system in terms of power.	10.10 Power
-----------	---	-------------

Unit 4: Linear Momentum (4 topics) AP® Physics 1 Course Framework		
Торіс	Learning Objectives	College Physics: A Strategic Approach Chapters and Sections
4.1 Linear Momentum	4.1.A Describe the linear momentum of an object or system.	9.2 Momentum and the Impulse-Momentum Theorem
4.2 Change in Momentum and Impulse	 4.2.A Describe the impulse delivered to an object or system. 4.2.B Describe the relationship between the impulse exerted on an object or a system and the change in momentum of the object or system. 	 9.1 Impulse 9.2 Momentum and the Impulse-Momentum Theorem 9.3 Solving Impulse and Momentum Problems
4.3 Conservation of Linear Momentum	4.3.A Describe the behavior of a system using conservation of linear momentum.	9.4 Conservation of Momentum 9.6 Momentum and Collisions in Two Dimensions
4.4 Elastic and Inelastic Collisions	4.4.A Describe whether an	9.5 Inelastic Collisions 9.6 Momentum and Collisions in Two Dimensions 10.9 Energy in Collisions



7

interaction between objects is elastic or inelastic.	

Unit 5: Torque and Rotational Dynamics (6 topics) AP® Physics 1 Course Framework		
Торіс	Learning Objectives	College Physics: A Strategic Approach Chapters and Sections
5.1 Rotational Kinematics	5.1.A Describe the rotation of a system with respect to time using angular displacement, angular velocity, and angular acceleration.	7.1 Describing Circular and RotationalMotion7.2 The Rotation of a Rigid Body
5.2 Connecting Linear and Rotational Motion	5.2.A Describe the linear motion of a point on a rotating rigid system that corresponds to the rotational motion of that point, and vice versa.	7.1 Describing Circular and RotationalMotion7.2 The Rotation of a Rigid Body
5.3 Torque	5.3.A Identify the torques exerted on a rigid system.5.3.B Describe the torques exerted on a rigid system.	7.3 Torque 7.4 Gravitational Torque and the Center of Gravity



8

5.4 Rotational Inertia	 5.4.A Describe the rotational inertia of a rigid system relative to a given axis of rotation. 5.4.B Describe the rotational inertia of a rigid system rotating about an axis that does not pass through the system's center of mass. 	7.5 Rotational Dynamics and Moment of Inertia
5.5 Rotational Equilibrium and Newton's First Law in Rotational Form	5.5.A Describe the conditions under which a system's angular velocity remains constant.	5.1 Equilibrium 8.1 Torque and Static Equilibrium
5.6 Newton's Second Law in Rotational Form	5.6.A Describe the conditions under which a system's angular velocity changes.	7.5 Rotational Dynamics and Moment of Inertia 7.6 Using Newton's Second Law for Rotation
Unit 6: Energy and Mom	entum of Rotating Systems	s (6 topics) AP® Physics 1 Course
Framework		
Framework Topic	Learning Objectives	College Physics: A Strategic Approach Chapters and Sections
Framework Topic 6.1 Rotational Kinetic Energy	Learning Objectives 6.1.A Describe the rotational kinetic energy of a rigid system in terms of the rotational inertia and angular velocity of that rigid system.	College Physics: A Strategic Approach Chapters and Sections 10.3 Kinetic Energy
Framework Topic 6.1 Rotational Kinetic Energy 6.2 Torque and Work	Learning Objectives6.1.A Describe the rotational kinetic energy of a rigid system in terms of the rotational inertia and angular velocity of that rigid system.6.2.A Describe the work done on a rigid system by a given torque or collection of torques.	College Physics: A Strategic Approach Chapters and Sections 10.3 Kinetic Energy (none)



9

	6.3.B Describe the angular impulse delivered to an object or rigid system by a torque.	
	6.3.C Relate the change in angular momentum of an object or rigid system to the angular impulse given to that object or rigid system.	
6.4 Conservation of Angular Momentum	 6.4.A Describe the behavior of a system using conservation of angular momentum. 6.4.B Describe how the selection of a system determines whether the angular momentum of that system changes. 	9.7 Angular Momentum

Unit 6: Energy and Momentum of Rotating Systems (6 topics) AP® Physics 1 Course Framework		
Торіс	Learning Objectives	College Physics: A Strategic Approach Chapters and Sections
6.5 Rolling	 6.5.A Describe the kinetic energy of a system that has translational and rotational motion. 6.5.B Describe the motion of a system that is rolling without slipping. 6.5.C Describe the motion of a system that is rolling while slipping. 	7.7 Rolling Motion 10.3 Kinetic Energy



6.6 Motion of Orbiting	6.6.A Describe the	(none)
Satellites	motions of a system	
	consisting of two objects	
	interacting only via	
	gravitational forces.	

Unit 7: Oscillations (4 topics) AP® Physics 1 Course Framework			
Торіс	Learning Objectives	College Physics: A Strategic Approach Chapters and Sections	
7.1 Defining Simple Harmonic Motion (SHM)	7.1.A Describe simple harmonic motion.	14.1 Equilibrium and Oscillation 14.2 Linear Restoring Forces and SHM	
7.2 Frequency and Period of SHM	7.2.A Describe the frequency and period of an object exhibiting SHM.	14.1 Equilibrium and Oscillation 14.4 Energy in Simple Harmonic Motion 14.5 Pendulum Motion	
7.3 Representing and Analyzing SHM	7.3.A Describe the displacement, velocity, and acceleration of an object exhibiting SHM.	14.3 Describing Simple Harmonic Motion	



11

7.4 Energy of Simple	7.4.A Describe the	14.4 Energy in Simple Harmonic Motion
Harmonic Oscillators	mechanical energy of a system exhibiting SHM.	

Unit 8: Fluids (4 topics) AP® Physics 1 Course Framework			
Торіс	Learning Objectives	College Physics: A Strategic Approach Chapters and Sections	
8.1 Internal Structure and Density	8.1.A Describe the properties of a fluid.	13.1 Fluids and Density	
8.2 Pressure	8.2.A Describe the pressure exerted on a surface by a given force.	13.2 Pressure	
	8.2.B Describe the pressure exerted by a fluid.		



12

8.3 Fluids and Newton's Laws	 8.3.A Describe the conditions under which a fluid's velocity changes. 8.3.B Describe the buoyant force exerted on an object interacting with a fluid. 	13.3 Buoyancy
8.4 Fluids and Conservation Laws	 8.4.A Describe the flow of an incompressible fluid through a cross-sectional area by using mass conservation. 8.4.B Describe the flow of a fluid as a result of a difference in energy between two locations within the fluid–Earth system. 	13.4 Fluids in Motion 13.5 Fluid Dynamics

